

American Center for Mobility

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Why Connected & Autonomous Vehicles (CAVs) at all ??

SAFETY



40,000 Fatalities in 2017
94 % of crashes are Human Error

Quality of Life
& Environment



7 Billion Hours in Traffic

Over **1 Metric Ton** of CO2 Emissions

Economy



Congestion costs **\$ 160 Billion** per year
Transportation **\$1.4 Trillion** Industry
63 Tons of Freight per year/per person



Where are We Going with Transportation Vehicles ?



Personal Mobility Vehicles of the Future ?



What is the Future of the Transportation Infrastructure ?

A system without Signals ?

A system without signs ?

Will Pavement marking be needed ?

New Highway Designs ?

Continuous vehicle platooning ?



CAVs are Leading the Transformation

- Saves Lives
- Saves Time
- Protects Environment
- Creates Value
- Changes Society



American Center for Mobility
CONNECTED. AUTOMATED. VALIDATED.



Working Definitions

- Connected Vehicle

- A vehicle that is able to share and receive data with other vehicles, other road users, and the road infrastructure itself

- Autonomous Vehicle

- A vehicle that uses onboard sensing, maps, and algorithms to operate the vehicle with no driver interaction required.

Connected + Automated = CAV



Connected & Automated Vehicles

- Recent high profile crashes have garnered significant attention
- Significant technical and policy challenges remain including methods for testing and validation
- Voluntary standards will be needed for AVs and related equipment
- Technology is moving fast
- Education is critical



How a Self-Driving Uber Killed a Pedestrian in Arizona



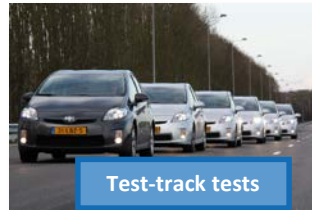
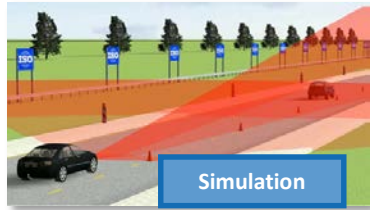
Waymo's Self-Driving Car Crash Revives Hard Questions



Technology Validation is Challenging 'On Road'

Validation Challenges:

- ✓ “Unlimited” number of possible scenarios
- ✓ System-critical situations rarely happen while on road
- ✓ Scenarios often not easily reproducible while on road
- ✓ “Scenarios often too dangerous/complicated to test on road



tass international

prescan



The new testing challenge is cross-disciplinary

Connected & Automated Vehicles

“Traditional” Vehicles

(Systems)

(Driving Task)

(Decision Making)

Mechanical
engineering

Electrical
engineering

Software
engineering

HMI

Cybersecurity

Wireless &
Telecoms

Infrastructure/ civil
engineering

Optics

Big Data
management

Urban planning

Behavioral sciences

Other...

Traditional Proving Ground

AV Proving Ground



Needed: Next Generation Proving Ground

- **Traditional** proving grounds are typically designed for single vehicle tests such as:

- ✓ Durability tests
- ✓ Noise Vibration & Harshness (NVH) tests
- ✓ Ride & handling tests
- ✓ Skid tests
- ✓ Etc.



- But for CAV's, **Next Generation Test Facilities** with additional capabilities are needed to:

- ✓ Test the vehicle's environmental perception
- ✓ Test the interaction of the vehicle with real world road-infrastructure
- ✓ Test with large amounts of vehicles
- ✓ Test with other types of road users
- ✓ Test with multiple (competing) companies



What is the American Center for Mobility?

Non-profit, Purpose Built, Next Generation Automated Vehicle Proving Ground focused on:

1. Product development, testing and validating connected and automated vehicles and their security
2. Accelerating voluntary standards
3. Educating and training the workforce, public, and tech sector



TESTING



STANDARDS

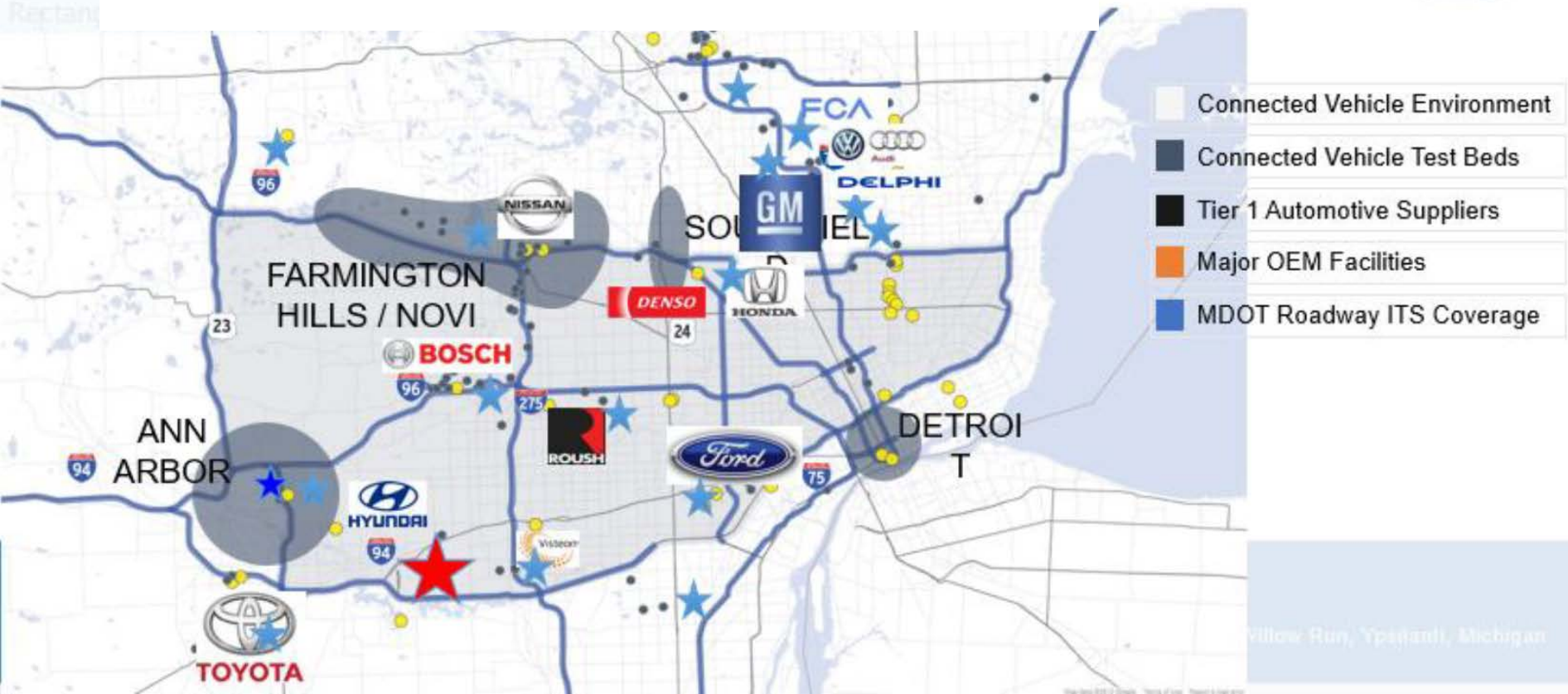
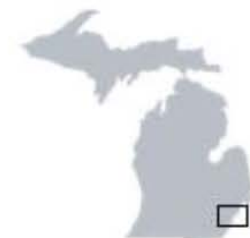


EDUCATION



Why Michigan, why now?

Southeast Michigan Auto Industry



ACM – Industry Investors

Total of 110 M\$ invested by State and Industry



ACM – Enabling Partners



Track Operations and
Testing Services



Exclusive Cellular Provider
(5G Pilot coming)



Data Manager and
Cloud Provider

Siemens PLM Software



Simulation & Engineering services



Siemens Mobility
Corporation

Signal and Communications Equipment

WILLOW RUN



The American Center for Mobility

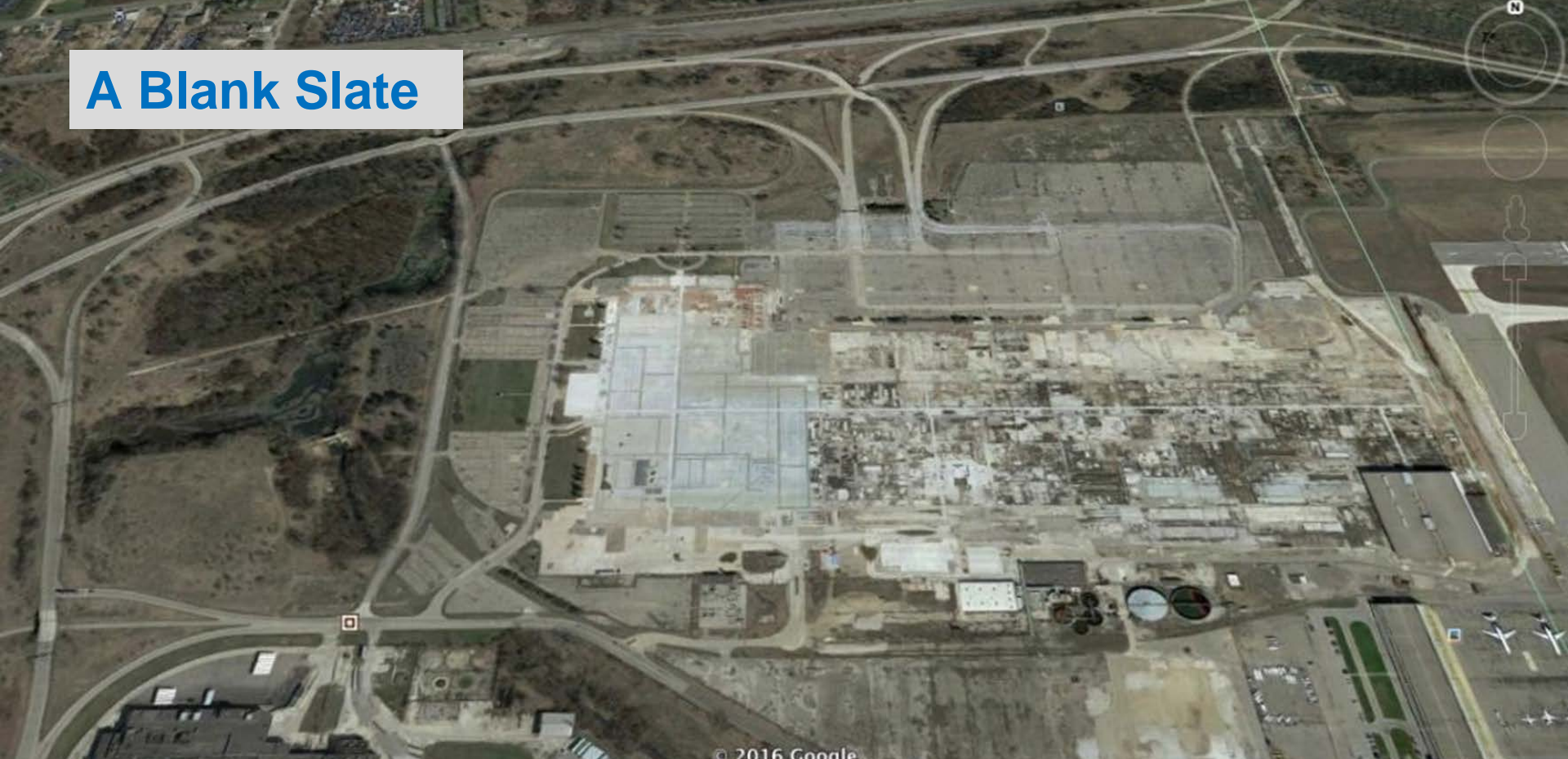
Willow Run, Ypsilanti, Michigan

Willow Run - a history of innovation



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CONNECTED. AUTOMATED. VALIDATED.

A Blank Slate



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Willow Run, Ypsilanti, Michigan

Pillars of Activities

TESTING



STANDARDS



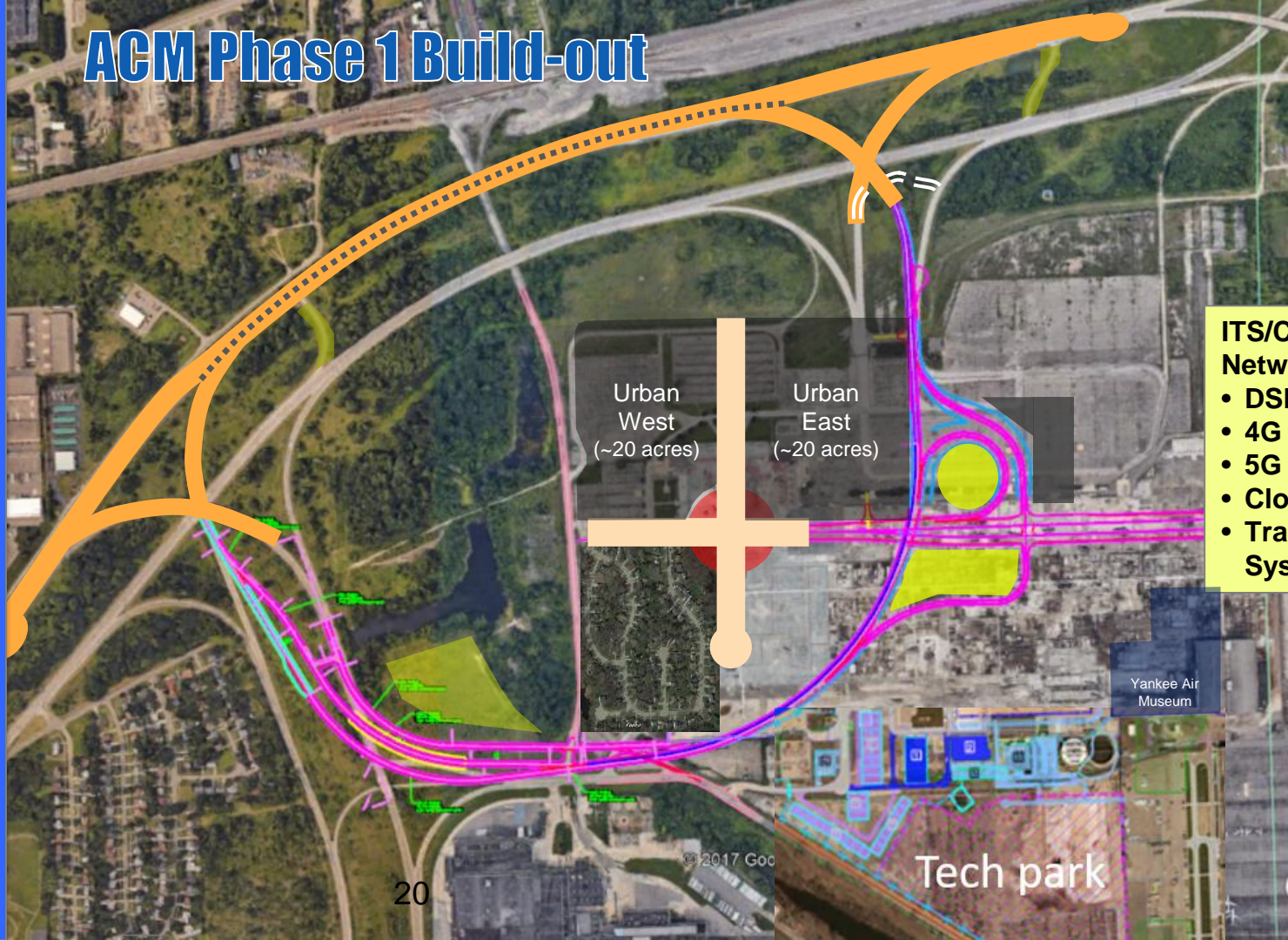
EDUCATION



ACM Phase 1 Build-out

Real world test infrastructure:

- 2.5 mile Highway Speed loop
- Full size Interchange
- 1.5 mile two lane arterial
- Triple overpasses
- 700' curved tunnel
- 6 lane Boulevard



- ITS/Comm Networks:**
- DSRC
 - 4G LTE
 - 5G (tbd)
 - Cloud
 - Traffic signal System

Urban West (~20 acres)

Urban East (~20 acres)

Yankee Air Museum

Tech park

ITS /Comm Network

AMERICAN CENTER FOR MOBILITY AT WILLOW RUN

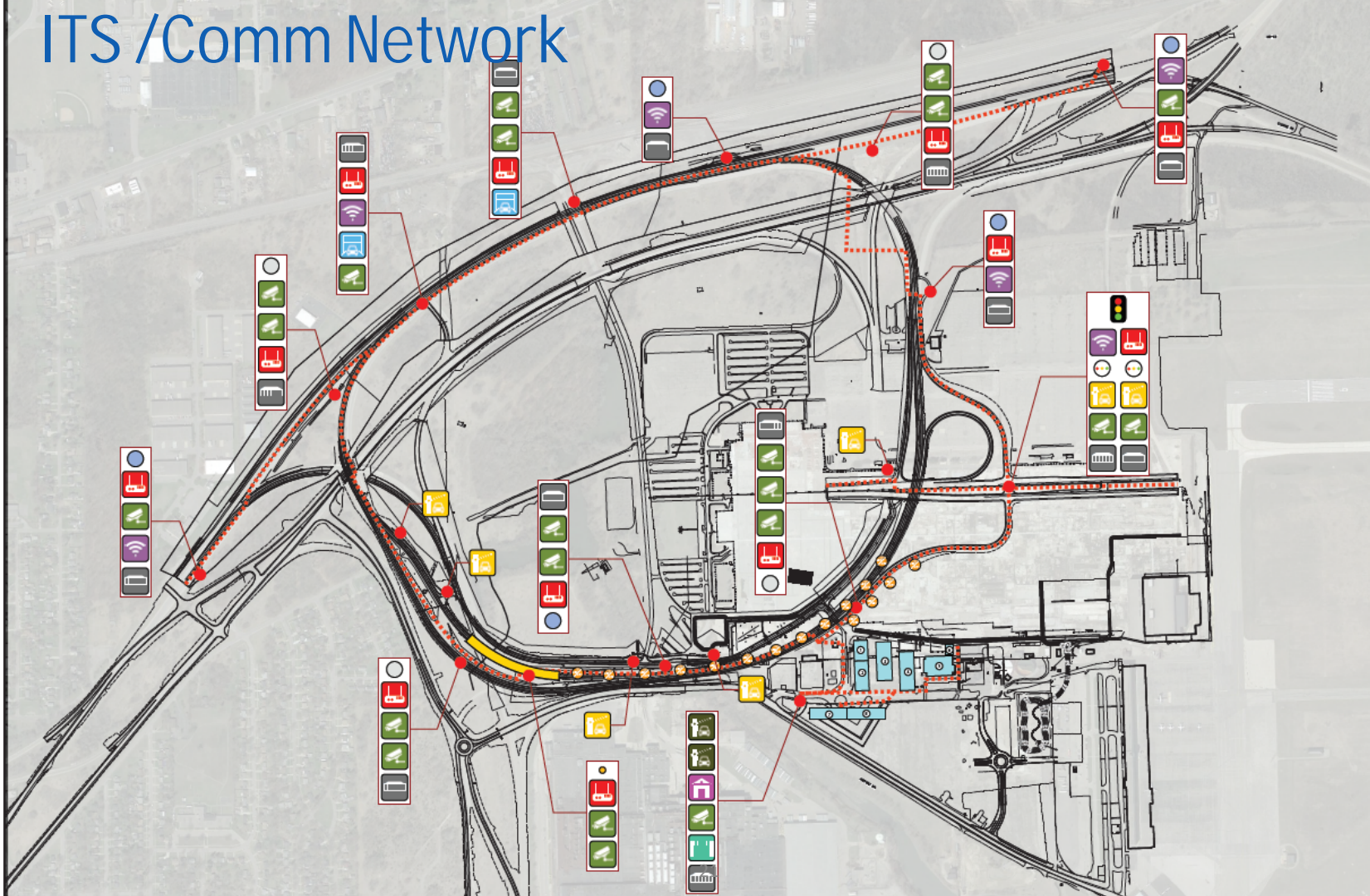
Intelligent Transportation System Phase 1A Final Layout
 Prepared By: WSP
 Feb 28 2018

LEGEND

- 6x **Wi-Fi Access Points**
Cisco Aironet 1560
- 21x **CCTV Camera**
Cofax HD Rse
- 12x **3.9 GHz DSRC Road Side Unit**
Lear Locomotive Roadstar RSU
- Dynamic Lane Control Signs (Future)**
- 14x **Field Ethernet Switch**
Arista Lucent OS6 B5-104X
- 7x **Barrier Gate System**
Hy Security
- 2x **Barrier Gate System with Intercom/Camera**
Hy Security
- ACM Guard Shack**
- Main Gate**
- 4x **90' SPUN CONCRETE POLE**
- 2x **TRAFFIC SIGNAL MAST ARM POLE**
- 5x **40' STRAIN POLE**
- 40' ROADWAY LIGHTING POLE**
 - Light Emitting Diode (LED) - Wireless Control
 Eaton - 18V2 LED/CM/CM - Lighting Controls
 - High Pressure Sodium (HPS)
 Eaton - OVZ Drop Lantz Refractor
- 16x **Tunnel Lights LED**
Holephone - TMLED 9 4K 1 AS CLN DGR 5 DM F1
- 14x **Traffic Signal Controller**
Slemco m-60 Traffic Signal Controller
- 96 STRAND FIBER OPTIC CABLE**

BUILDINGS

- SPS 18 (FUTURE)**
- SPS 1A**
- SPS 2 (FUTURE)**
- SPS 3 (FUTURE)**
- MAINTENANCE BUILDING**
- TEMPORARY OPERATION CENTER (LTS)**
- 1A**
- LTS 18 (FUTURE)**



Safe validation must include a structured combination of three methodologies

Controlled track testing



Computer Simulation - **prescan**[®]

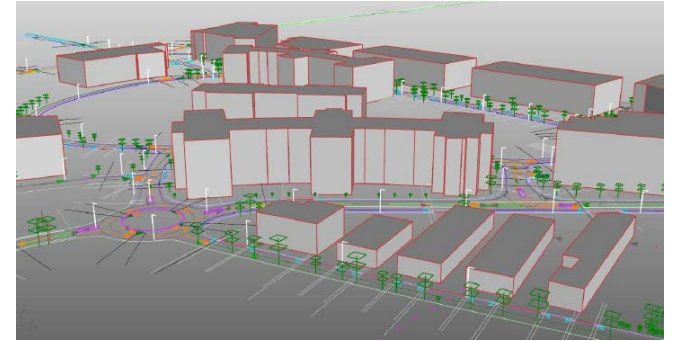
On-road testing & operation



Test environments – simulated

3D Mapping Solutions – ultraHD point cloud, color imagery

Siemens PLM / TASS PreScan



Data Management & Analytics Platform (DMAP)

Microsoft Azure

Scenario development

Data segregation / access control

Decreased development cycle time

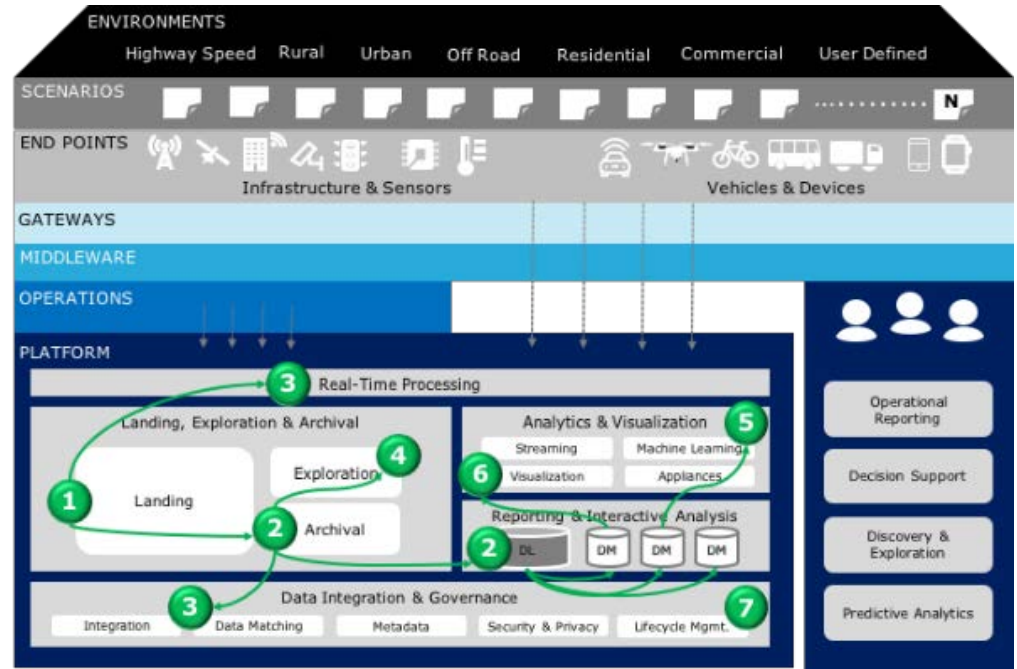
Visualization

On-track testing

Public-road data collection

Evaluate CAV safety, energy efficiency, advanced control algorithms in controlled and real-world settings

Single vehicle or small fleet experiments



Pillars of Activities

TESTING



STANDARDS



EDUCATION



AV Validation – Policy & Standards

Unanswered questions:

How safe is safe enough?

When is a test vehicle safe enough to go out on the public roads?

How will we validate that an AV is ready for public sale and use?

How are in-service updates, repairs, and aftermarket solutions validated?



Industry and government collaborate on standards

technical expertise



**Next Generation Proving Grounds
accelerate this process**



voluntary standards



regulation



Pillars of Activities

TESTING



STANDARDS

SAE
INTERNATIONAL

ite



EDUCATION



ACM Academic Consortium



Four Key Education Needs

Workforce



- Professional development
- “NextTraining” for displaced workers
- Veterans Next Training
- Ongoing Training & Certification
- “Boot camp”

Public & K-12



- General Public
- Seniors
- STEM Students
- Disabled & Underserved Communities
- Dealers
- First Responders

Higher Ed



- Direct hands-on experience for students
- Co-ops, internships, summer jobs, recruitment opportunities

R&D



- Collaboration in pre-competitive research
- Joint funding opportunities and research



Original



1944



12/2003

Revised

2003



Image Landsat / Copernicus
Image © 2018 DigitalGlobe

Google Earth

Imagery Date: 12/30/2003 42°14'21.50" N 83°33'04.08" W elev 0 ft eye alt 3602 ft

1999



Reclaimed

2016



Google Earth

Imagery Date: 4/7/2017 42°14'27.99" N 83°33'22.52" W elev 720 ft eye alt 3602 ft

Repurposed



2018



Reopened: December 11, 2017



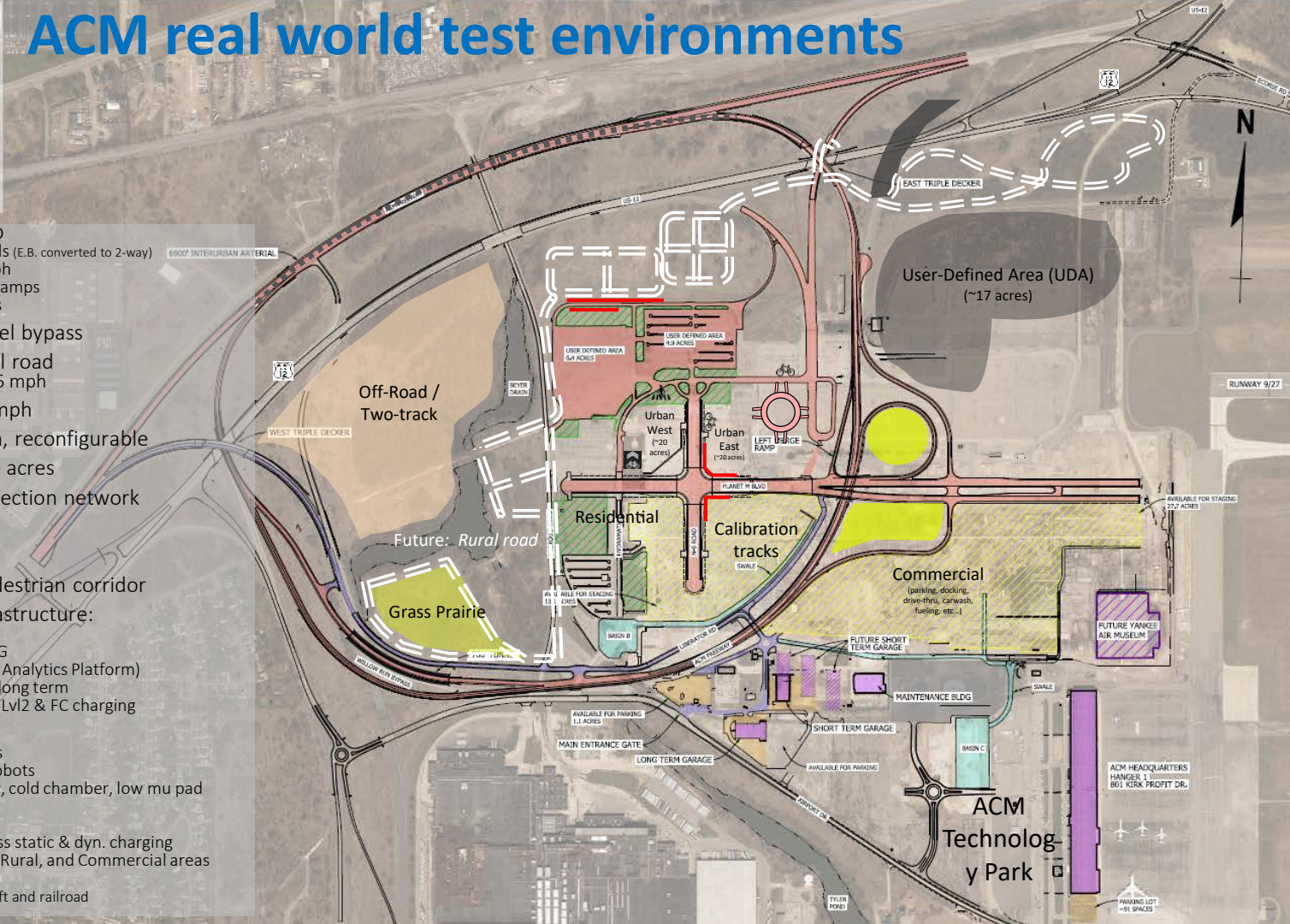
[2017]



ACM real world test environments

LEGEND	
	- TEST ROAD
	- ACCESS ROAD
	- ACM CAMPUS
	- AVAILABLE ACREAGE
	- PARKING
	- BASIN
	- GRASS
	- BLDG

- 2.5 mile Highway loop
 - Former public roads (E.B. converted to 2-way)
 - 2+ lanes, 50-65 mph
 - Exit and entrance ramps
 - Triple-deck bridges
- 700 foot curved Tunnel bypass
- 1.5 mile urban arterial road
 - 2 lanes, 2-way 55 mph
- 6-lane boulevard 55 mph
- 6 x 6 lane intersection, reconfigurable
- User-defined area, 8+ acres
- Urban canyon / intersection network
- Parking environment
- Roundabout, 2-lane
- 0.5 mile Bicycle & Pedestrian corridor
- Network & other infrastructure:
 - DSRC (15 RSUs)
 - 4G LTE (private), 5G
 - Cloud (Data Mgt & Analytics Platform)
 - Garages - short & long term
 - 90MW substation; Lvl2 & FC charging
- Under development:
 - Guided soft targets
 - Braking/steering robots
 - Weather simulator, cold chamber, low mu pad
 - Signalized corridor
 - Cybersecurity Lab
 - xFC station, wireless static & dyn. charging
 - Residential, 2 mile Rural, and Commercial areas
 - Technology Park
 - Multi-mode: aircraft and railroad



The logo for Planet M features the word "planet" in a light green, lowercase, sans-serif font, followed by a large blue circle containing a white lowercase "m". Below the logo is the tagline "Michigan. Where big ideas in mobility are born." in a white, sans-serif font. The background is a dark blue gradient with various white icons in circles, including a car, a smartphone, a location pin, a traffic light, a train, a truck, a helicopter, a road tunnel, a speedometer, a hand pointing at a screen, a document, and a car's front view.

planet **m**

Michigan. Where big ideas in mobility are born.®

**Mark A. Chaput P.E.
American Center for Mobility**

**PLANET M Website
www.planetm.com**